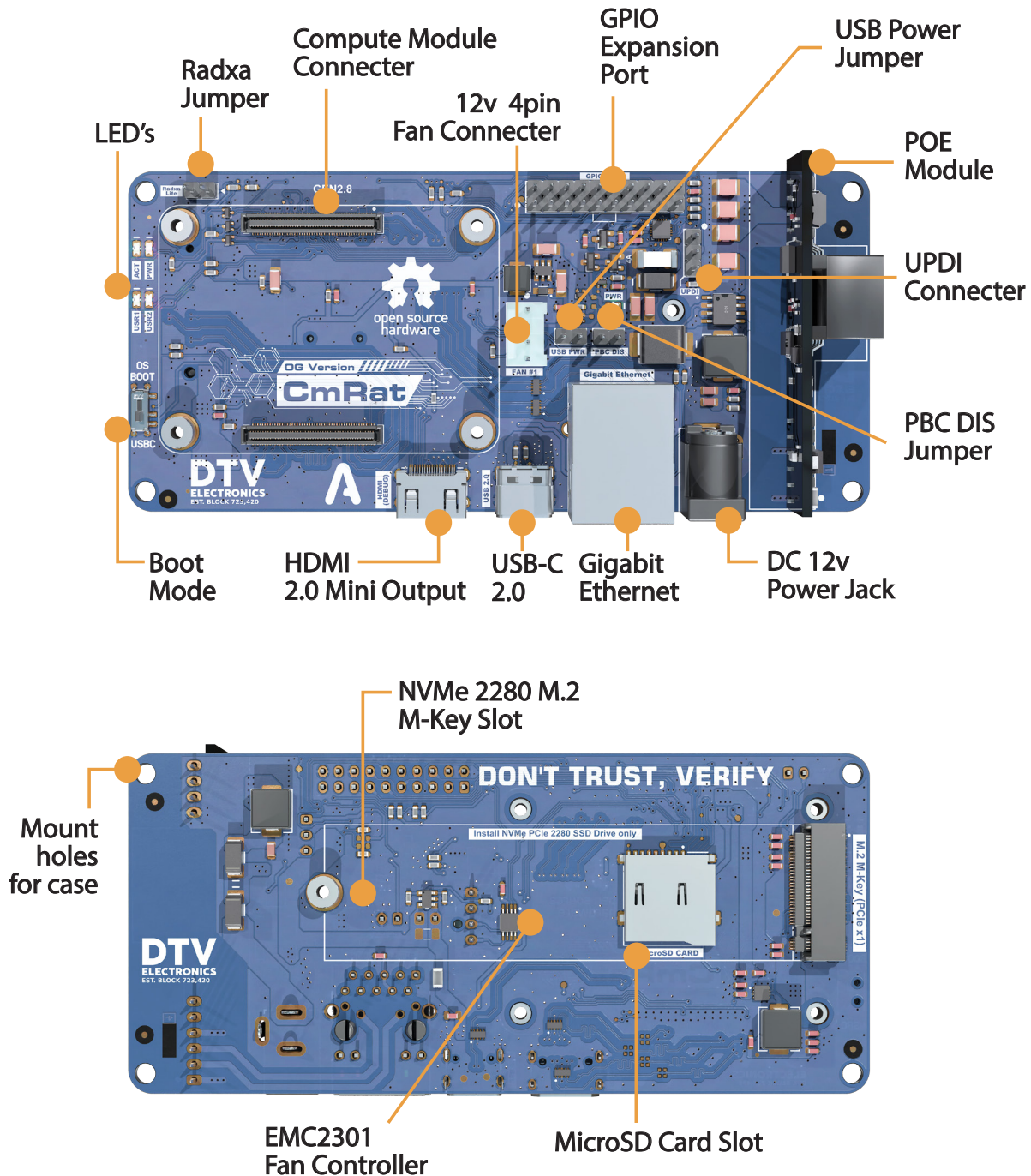


CmRat Introduction

A versatile & high-performance carrier board that supports a wide range of compute modules such as the Raspberry Pi CM4/CM5 and Radxa CM3/CM5.

This makes for an easy to build and use powerful PCB for flexible embedded systems and custom setups for a wide variety of use cases.



LED's

- **ACT** – Blinks to show activity on the board
- **PWR** – Shows that power is connected
- **USR1 / USR2** – User-customizable LEDs (behavior depends on OS and your configuration)

💡 You can configure these LEDs through GPIO or OS-level scripts, depending on the system you use.

Power & Cooling

12v Fan Connector

Standard 4-pin header to connect a 12V fan for active cooling.

💡 Useful when overclocking or running heavy workloads on CM's.

DC Power Jack (12V)

Use a standard 12V DC adapter with a 2.1mm barrel plug. Recommended: **12V @ 1A** (same as PoE power spec).

⚠️ Avoid higher voltages or currents – it may damage your board!

PoE Module

Optional module for **Power over Ethernet (PoE)**. Complies with IEEE802.3af (Class 0: 0.44W to 12.95W).

✅ Saves you from using a separate power cable – power and Ethernet in one!

Compute & Booting

Compute Module connector

Two 100-pin mezzanine connectors for installing a Raspberry Pi CM5 module.

Boot Mode Switch

Choose the boot source:

- **'OS Boot'** – boots from storage on the Compute Module (eMMC, MicroSD, NVMe)
- **'USB-C'** – connect to a PC and flash the OS or access the CM5 directly

Storage Options

MicroSD Card Slot

Alternative OS install method or extra storage.

✅ Great for testing builds before committing to eMMC/NVMe.

NVMe M.2 Slot (2280 M-Key)

Full-size NVMe SSD support.

Tested with **2TB**, should also work with larger (4/8TB) drives.

💡 Make sure your OS supports NVMe boot if you're not using eMMC.

Connectivity

Gigabit Ethernet

Standard RJ45 port for wired internet.

💡 Combine with PoE to simplify wiring in enclosures.

USB-C 2.0 Port

For USB devices (e.g. keyboards, storage) or power (see jumper config).

HDMI 2.0 Output

Connect a monitor or TV – if supported by your OS.

💡 Great for debugging or graphical applications.

Expansion & Add-ons

GPIO Expansion Header

20 pins exposed for connecting sensors, buttons, relays, etc.

💡 Can also act as a serial/debug console depending on OS config.

UPDI connector

For programming the onboard ATtiny806 microcontroller (Microchip) using UPDI protocol.

💡 Needed only if you're modifying the board-level firmware or using the ATtiny for automation. The board itself can also work independently if CM is meant to just run out of the box.

EMC2301 Fan Controller

The I²C fan speed controller and monitor.

✅ Supports PWM fans and temperature-based speed profiles.

Jumpers (Optional Settings)

USB PWR Jumper

Allows powering the board from a 5V USB-C power adapter.

✅ Perfect for development benches – no need for DC jack or PoE.

PBC DIS Jumper

When enabled (default), the board powers on automatically once any power source is connected.

💡 Remove this jumper if you want to control power manually via a switch or onboard microcontroller.

Radxa Jumper

Enable only if you're using Radxa CM3 modules that boot from MicroSD.

⚠️ Not needed for Raspberry Pi Compute Modules.

Mounting

Mounting Holes

Standard mounting points for installing the board into an enclosure or custom case.

Schematics / Technology/Assembly Cards

Please see GitHub for the latest documents.

BOM List

Please refer to the Github repository for an updated BOM list.

Source/Output Files

Please refer to the Github repository for source files.



Supporters/Contributors

Adam of 'Anlumen Technologies'
Mirek of 'PineBoards'
Leo of 'BuryRoadLabs'
Aaron Dewes - Master Developer